

Dynamics of a population of interacting plant and pollinator species

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Motivations

- ★ Bees play a major role in the pollination of plants.
- ★ Fear that the extinction of some bees species ends in a cascade of extinction in bees and plants species.
- ★ We consider a bipartite network of bee and plant species:
 - ▶ fixed in time
 - ▶ model population dynamics with interactions along the graph

Will a large complex system be stable? (R. May, 1972)

Ecological stability by May (1972)

★ Consider a graph with n vertices (species) and connectance

$$C = \frac{|E|}{n(n-1)}.$$

★ Assume that around the equilibrium:

$$N_t^i = \hat{N}^i + x_t^i, \quad \text{with} \quad \frac{dx^i}{dt} = \sum_{j=1}^n a_{ij} x_j(t),$$

where

- ▶ $a_{ii} = -1$,
- ▶ $a_{ij} = 0$ if there is no edge between species i and j ,
- ▶ a_{ij} is an independent centered r.v. with variance s^2 , if $i \sim j$.

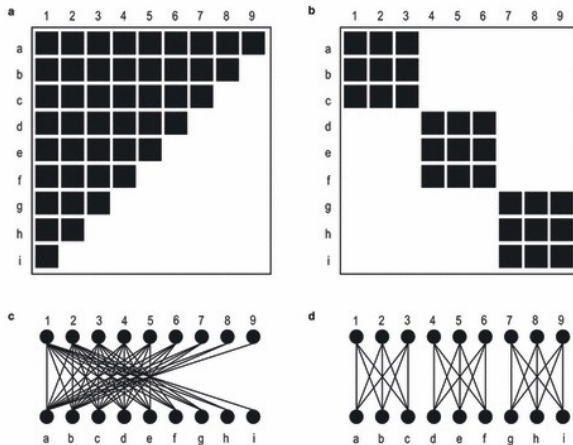
★ The system is stable if the eigenvalues of (a_{ij}) are negative.

May says that an equilibrium of the population is stable if and only if

$$s\sqrt{nC} < 1.$$

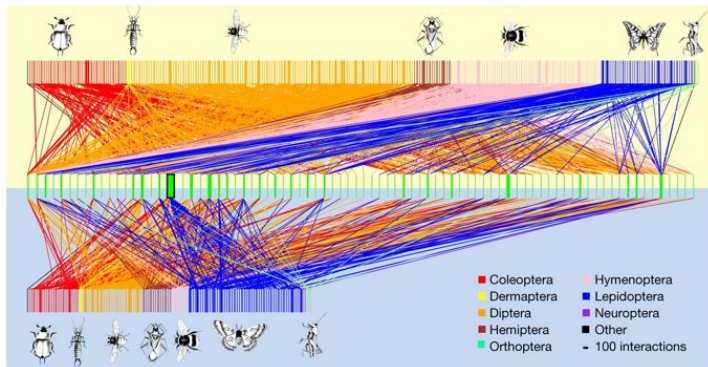
Shapes of plant-pollinator graphs

★ The networks are sometimes distinguished by **nestedness** and **connectance**.



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Knop, Zoller, Ryser, Gerpe, Hörler, Fontaine (2017)

Model of pollinator and plant

★ Structuration by **degree of specialization** of the species, x (plants) or y (bees) in $[0, 1]$.

★ We have n populations of plants and m populations of pollinators.

$$\mathbf{P}_t^n(dx) = \frac{1}{n} \sum_{i=1}^n P_t^i \delta_{x^i}(dx), \quad \mathbf{A}_t^m(dy) = \frac{1}{m} \sum_{j=1}^m A_t^j \delta_{y^j}(dy).$$

★ Rescaling parameter K :

$$\mathbf{P}_t^{K,n}(dx) = \sum_{i=1}^n \frac{1}{nK} P_t^{K,i} \delta_{x^i}(dx), \quad \mathbf{A}_t^{K,m}(dy) = \sum_{j=1}^m \frac{1}{mK} A_t^{K,j} \delta_{y^j}(dy).$$

→ Three parameters: K , n , m

Modelling a bipartite graph

★ **Vertices:** each pollinator and plant species.

★ **Edges:** $i \sim j$ if the pollinator species j visits the plant species i .

d_A^j and d_P^i are the degrees of the species j and i .

★ **Graph:** The bipartite graph \mathcal{G} can be represented by an $n \times m$ adjacency matrix $G^{n,m}$, with $G_{ij}^{n,m} = 1$ if the pollinator specie j interacts with the plant specie i , i.e. $i \sim j$, and 0 otherwise.

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★ **Bipartite Erdős-Rényi graphs:** Each plant species i and pollinator species j are connected with the probability $\phi(x^i, y^j)$ independently of the other couples.

Examples: $\phi(x, y) = xy$ or $\phi(x, y) = \varphi(|x - y|)$.

Interactions along the graph

★ Growth rate=natural birth - natural death rates:

$$g^P(r) = \frac{\alpha_P r}{\beta_P + \gamma_P r} - (d_3 + d_4 r), \quad g^A(r) = \frac{\alpha_A r}{\beta_A + \gamma_A r} - \left(d_1 + \frac{d_2}{r}\right)$$

where r is the resources that a given species can obtain from its interactions.

★ $c_{ij}^{n,m}$ is a weight for the interaction $i \sim j$:

$$R_t^{i,nm} = \sum_{j \sim i} c_{ij}^{n,m} A_t^j P_t^i.$$

★ A death by competition for the bees:

$$\sum_{\ell=1}^m H(y, y^\ell) A_t^\ell.$$

Semi-martingales

★ for a test function f :

$$\begin{aligned}\langle \mathbf{P}_t^{K,n}, f \rangle &= \frac{1}{n} \sum_{i=1}^n \frac{1}{K} P_t^{K,i} f(x_i) \\ &= \langle \mathbf{P}_0^{K,n}, f \rangle + \int_0^t \frac{1}{n} \sum_{i=1}^n f(x_i) g^P(R_s^{K,i,nm}) \frac{1}{K} P_s^{K,i} ds + \sum_{i=1}^n f(x_i) M_t^{K,n,i,f},\end{aligned}$$

★ where $M^{K,n,i,f}$'s are square integrable martingales with

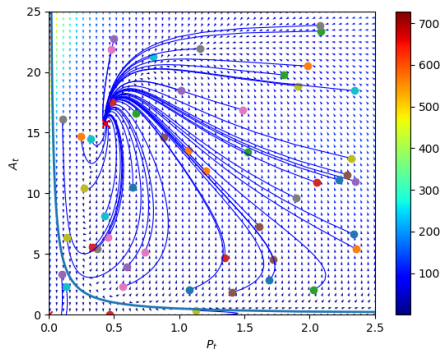
$$\langle M^{K,i,f} \rangle_t = \frac{1}{n^2 K} \sum_{i=1}^n f^2(x_i) \int_0^t \left(b^P(R^{K,i,nm}) + d^P(R^{K,i,nm}) \right) \frac{1}{K} P_s^{K,i} ds.$$

Large population limit

★ Large population limit for n, m fixed.

$$\frac{dP_t^i}{dt} = g^P \left(P_t^i \sum_{j \sim i} c_{ij}^{n,m} A_t^j \right) P_t^i$$

$$\frac{dA_t^j}{dt} = \left[g^A \left(A_t^j \sum_{i \sim j} c_{ij}^{n,m} P_t^i \right) - \sum_{\ell=1}^m H_m(y^j, y^\ell) A_t^\ell \right] A_t^j,$$

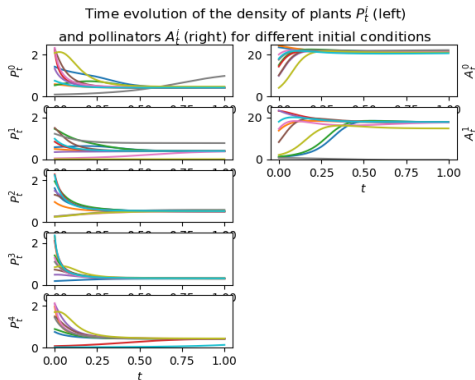


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Graphon convergence

★ For a 'small' motif F , let us define:

$$t(F, G) = \frac{|\text{inj}(F, G)|}{(n)_k}, \quad (n)_k = n(n-1) \cdots (n-k+1) = \frac{n!}{k!}$$

★ The class \mathcal{F} of isomorphism classes of finite graphs is denumerable and we denote by $(F_i)_{i \in \mathbb{N}}$ an enumeration.

★ We define a distance between graphs by:

$$d(G, G') = \sum_{i \in \mathbb{N}} 2^{-i} |t(F_i, G) - t(F_i, G')|.$$

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★ We can extend to the distance between G and a graphon ϕ with:

$$t(F, \phi) = \int_{[0,1]^k} \prod_{\{i,j\} \in E(F)} \phi(x_i, x_j) dx_1 \dots dx_k.$$

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Def: A sequence of graphs $(G_n)_{n \in \mathbb{N}}$ converges to the graphon ϕ if

$$\lim_{n \rightarrow +\infty} d(G_n, \phi) = 0.$$

Modelling the ressources

Recall:

$$R_t^{i,nm} = \sum_{j \sim i} c_{ij}^{n,m} A_t^j P_t^i.$$

★ **Hyp:** it is possible to index the plant and pollinator species s.t. for all $n, m \in \mathbb{N}^*$, there exists a continuous (random) function $c^{n,m} : [0, 1]^2 \mapsto \mathbb{R}$, s.t.

$$\forall i \in \{1, \dots, n\}, \forall j \in \{1, \dots, m\}, c_{ij}^{n,m} = c^{n,m}\left(\frac{i}{n}, \frac{j}{m}\right).$$

Moreover, we suppose that there exists a (random) function $c : [0, 1]^2 \mapsto \mathbb{R}$ such that the sequence of functions $c^{n,m}(\cdot, \cdot)$ converges to $c(\cdot, \cdot)$, when n and m tend to $+\infty$.

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★ **Example:** when the $c_{ij}^{n,m}$ depend on the degree of generalism:

$$c_{ij}^{n,m} = \rho(x^i, y^j) = \rho\left(F_{P,n}^{-1}\left(\frac{i}{n}\right), F_{A,m}^{-1}\left(\frac{j}{m}\right)\right).$$

Cinetic averaging of the graph

★ **Th:** Let us consider two independent sequences of i.i.d. random variables $(x^i)_{i \geq 1}$, $(y^j)_{j \geq 1}$ on $[0, 1]$, and good ICs. For $n, m \rightarrow +\infty$, $(\mathbf{P}_t^n(dx), \mathbf{A}_t^m(dx))_{t \geq 0}$ converge in $\mathcal{C}(\mathbb{R}_+, \mathcal{M}_F^2([0, 1]))$ to a process (\bar{P}, \bar{A}) in $\mathcal{C}(\mathbb{R}_+, \mathcal{M}_F^2([0, 1]))$, such that:

(i) for all $t \geq 0$, \bar{P}_t and \bar{A}_t admit densities $\bar{p}(x, t)$ and $\bar{a}(y, t)$ with respect to the Lebesgue measure on $[0, 1]$,

(ii) (\bar{P}, \bar{A}) is the unique solution, for $f \in \mathcal{C}([0, 1], \mathbb{R})$, of

$$\begin{aligned} \int_0^1 f(x) d\bar{P}_t(x) &= \int_0^1 f(x) d\bar{p}_0(x) dx \\ &\quad + \int_0^t \int_0^1 f(x) g^P \left(\bar{p}(x, s) \int_0^1 \rho(x, y) \phi(x, y) a(y, s) dy \right) \bar{p}(x, s) dx ds, \\ \int_0^1 f(y) d\bar{A}_t(y) &= \int_0^1 f(y) d\bar{a}_0(y) dy \\ &\quad + \int_0^t \int_0^1 f(y) \left[g^A \left(\bar{a}(x, s) \int_0^1 \rho(x, y) \phi(x, y) \bar{p}(x, s) dx \right) \right. \\ &\quad \left. - H * \bar{a}(y, s) \right] \bar{a}(y, s) dy ds. \end{aligned}$$

Thank You

